

# Automata with Timers

## FORMATS 2023

Véronique Bruyère, Guillermo A. Pérez, Gaëtan Staquet, Frits W. Vaandrager

Theoretical computer science  
University of Mons

Formal Techniques in Software Engineering  
University of Antwerp

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Many computer systems have **timing** constraints:

- ▶ Network protocols;
- ▶ Schedulers;
- ▶ Embedded systems;
- ▶ In general, **real-time** systems.

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In short: finite automata augmented with **clocks** that can be reset or used in guards along transitions and states.

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In short: finite automata augmented with **clocks** that can be reset or used in guards along transitions and states.

**BUT** timed automata are hard to construct and understand.

We focus on properties that can be represented with **timers**: automata with timers.

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- ▶ Learning (à la Angluin<sup>1</sup>) timed automata is challenging;
- ▶ Well-known model.

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- ▶ Automata with timers are more restrictive;
- ▶ Future work: learning algorithm;
- ▶ **This work** studies some properties of automata with timers.

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An **automaton with timers** (AT) is a tuple  $\mathcal{A} = (X, I, Q, q_0, \delta)$  where

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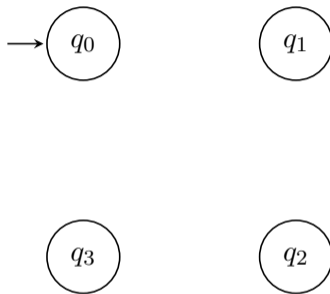


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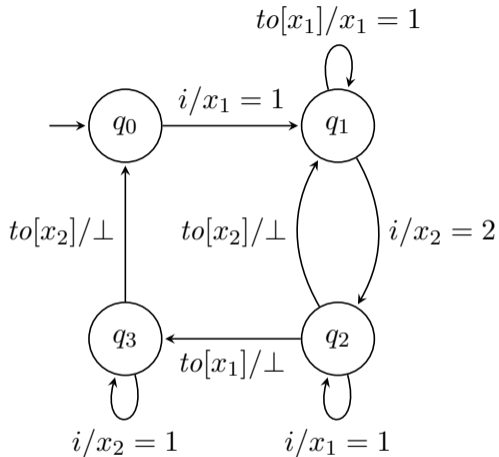


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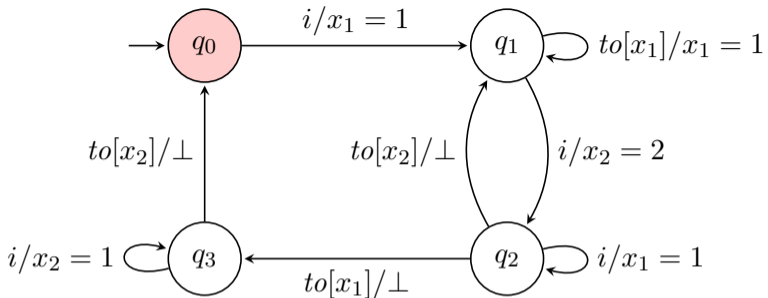


Figure 2: The same AT.

$(q_0, \emptyset)$

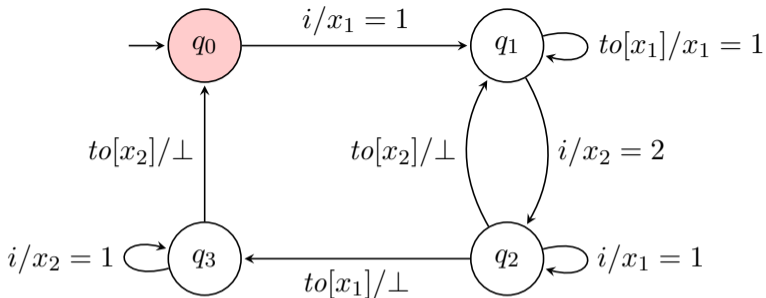


Figure 2: The same AT.

$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset)$$



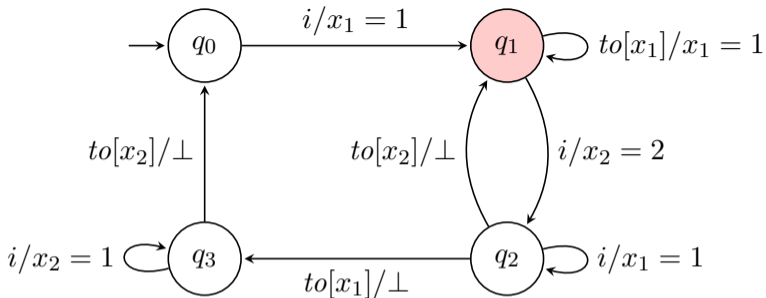


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$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow[x_{1,1}]{i} (q_1, x_1 = 1)$$

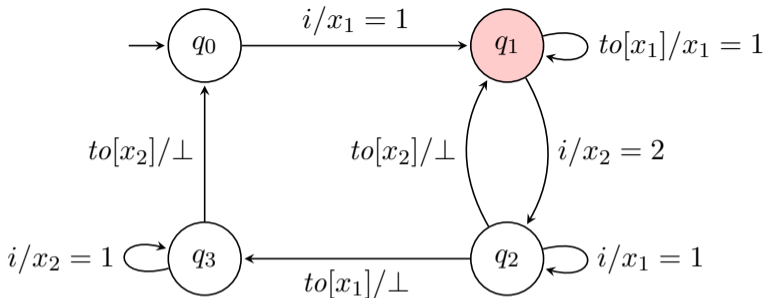


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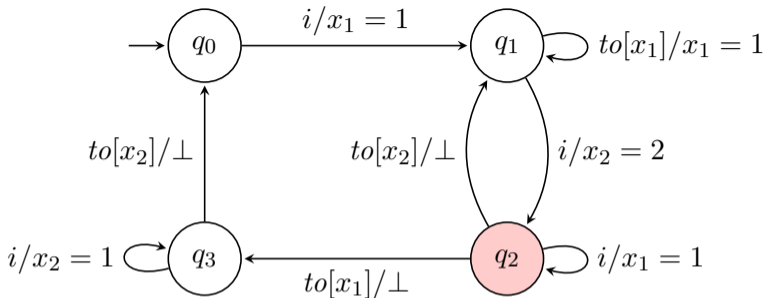


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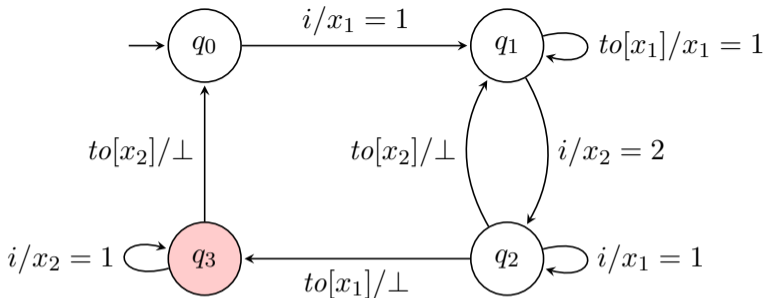


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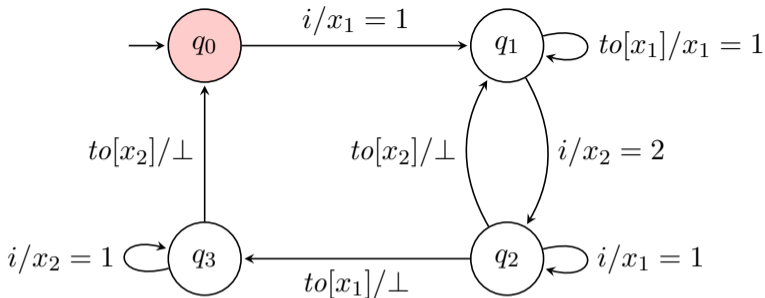


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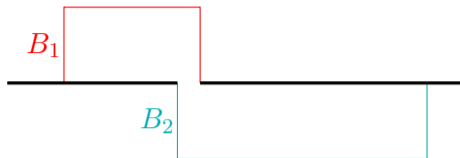


Figure 3: **Block** representation of the execution.

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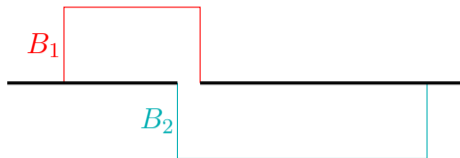


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We have **concurrent actions**.

We can avoid this concurrency and still see the **same sequence of actions**.

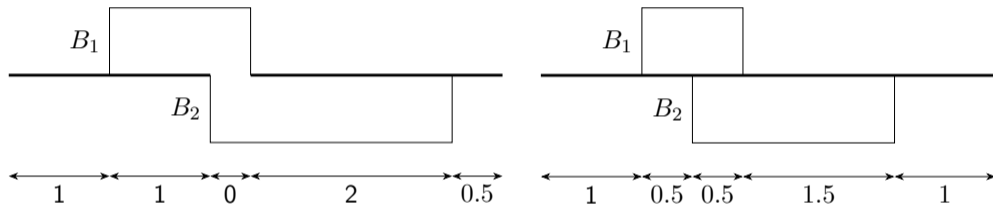


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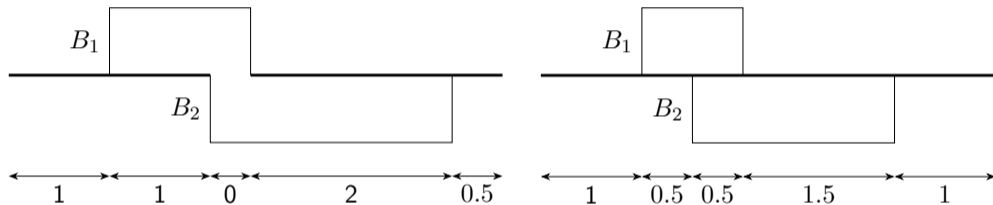


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Is it always possible?

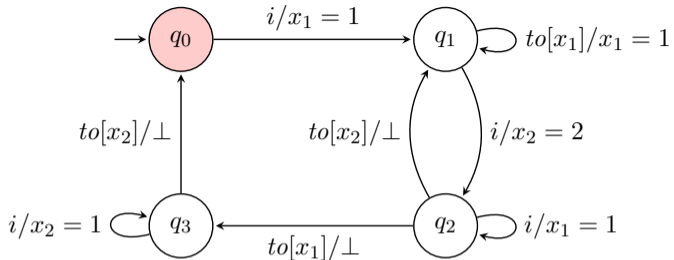


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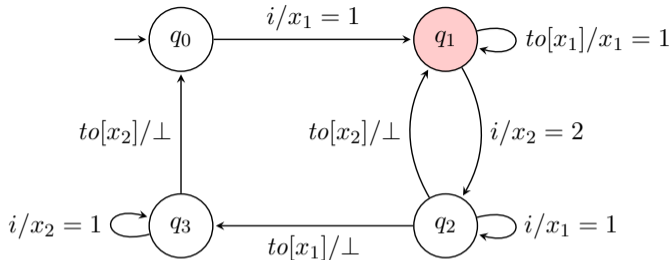


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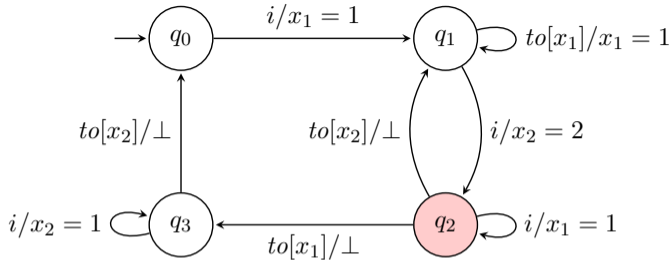


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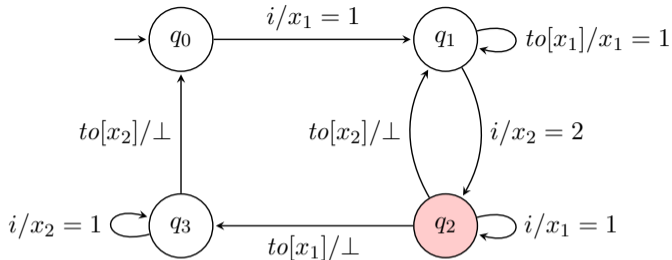


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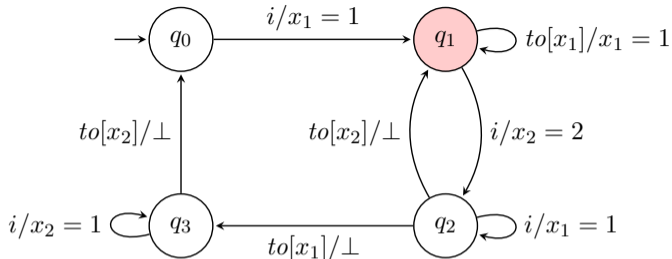


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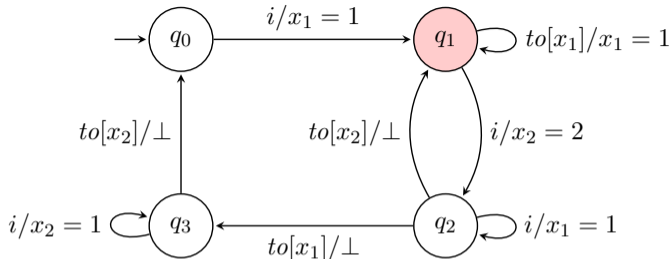


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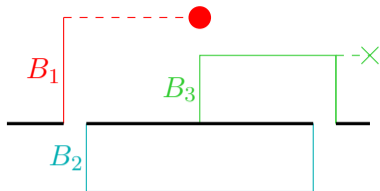


Figure 6: Block representation of the timed run.

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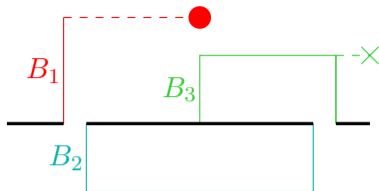
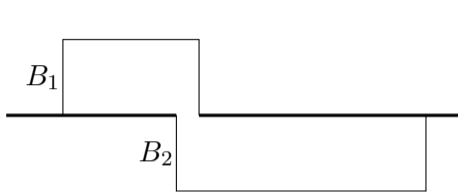


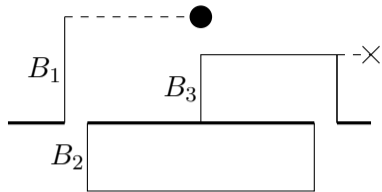
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We **cannot** avoid this concurrency and still see the same sequence of actions.

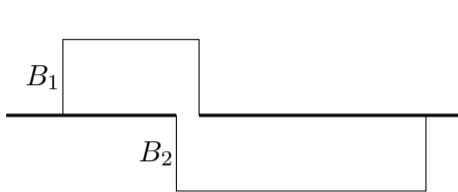


(a) Can be avoided.

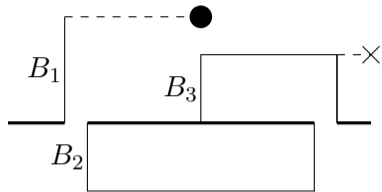


(b) Cannot be avoided.

Figure 7: Some concurrency can be **avoided**, some not.



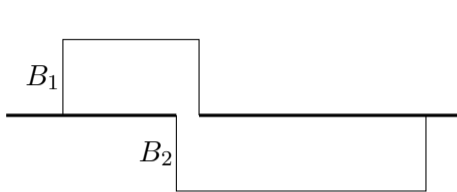
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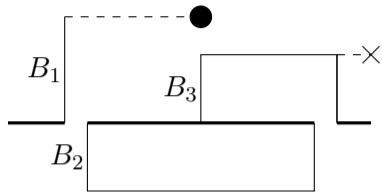
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Can we characterize when it is possible to remove the concurrency?



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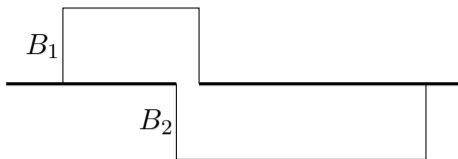
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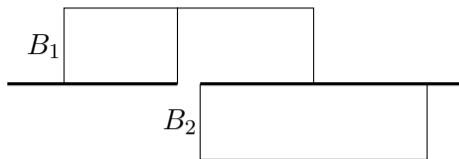
### Theorem 2 (Contribution)

*Deciding whether an AT contains an execution in which some concurrency **cannot** be avoided is PSPACE-hard and in 3EXP.*

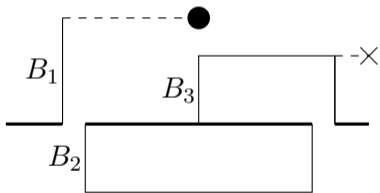




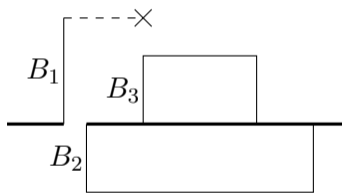
(a) Can be wiggled.



(b) Can be wiggled.

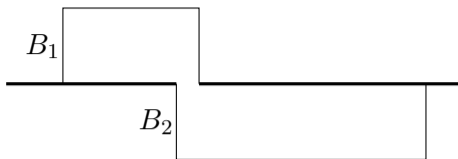


(c) Cannot be wiggled.

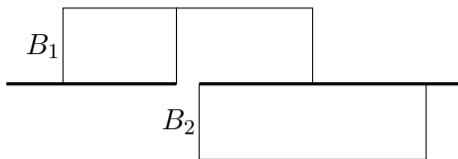


(d) Can be wiggled.

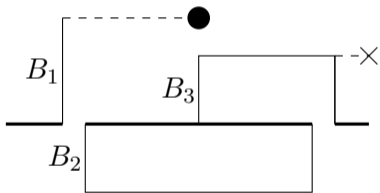
Figure 8: Not all runs can be wiggled.



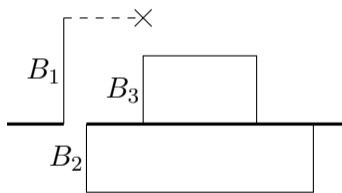
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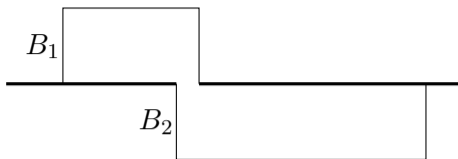


(c)  $B_1 \prec B_2, B_3 \prec B_1, B_2 \prec B_3$ .

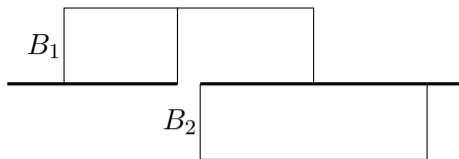


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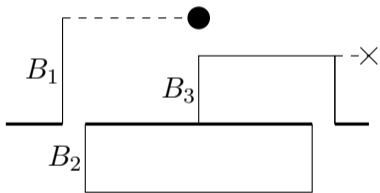
Figure 9: Define an **order**  $\prec$  over the blocks, based on races.



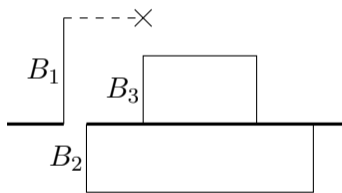
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(d)  $B_1 \prec B_2$ .

Figure 9: Define an **order**  $\prec$  over the blocks, based on races.

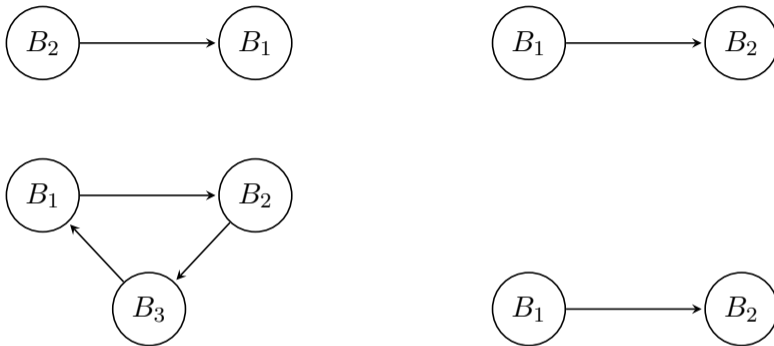


Figure 10: **Block graphs** defined from the blocks and  $\prec$ .

### Proposition 3 (Contribution)

*A timed run  $\rho$  can be wiggled if and only if its block graph is acyclic.*

$\Rightarrow$  By contraposition, we have a cycle.

If a block has...

- ▶ A predecessor? It cannot move left.
- ▶ A successor? It cannot move right.
- ▶ Both? It cannot move at all.

Thus,  $\rho$  cannot be wiggled since we have a cycle.

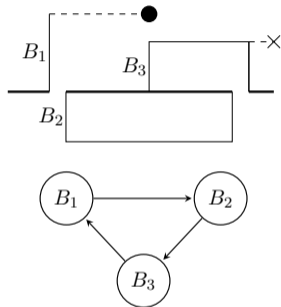


Figure 11: We have a cycle.

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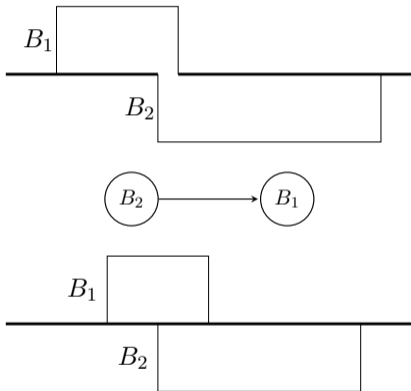


Figure 12: We change delays.

$\Leftarrow$  The graph is acyclic. Compute its topological sort and move the “last” block to the right.

$\hookrightarrow$  obtain  $\rho'$  with the same sequence of actions as  $\rho$  but  $\rho'$  contains **strictly less** races.

Repeat until all races are removed.

#### Theorem 4 (Contribution)

*An AT contains a run that cannot be wiggled if and only if the block graph of that run is cyclic.*

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- ▶ i.e., there are concurrent actions inducing a cyclic block graph.

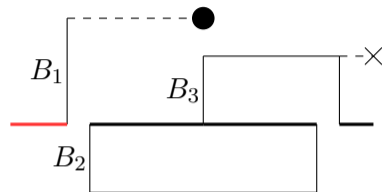
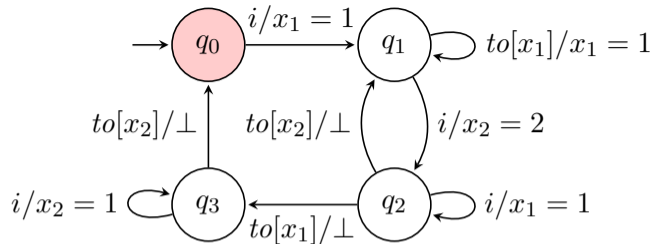
## Theorem 4 (Contribution)

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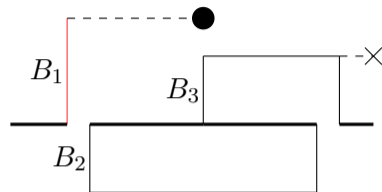
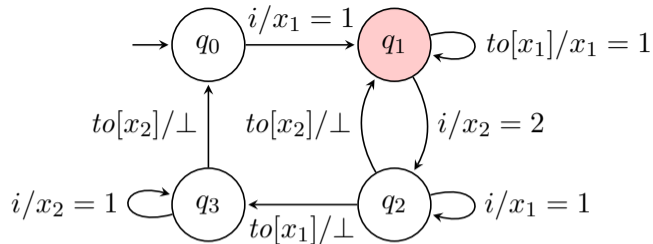
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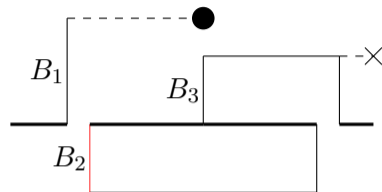
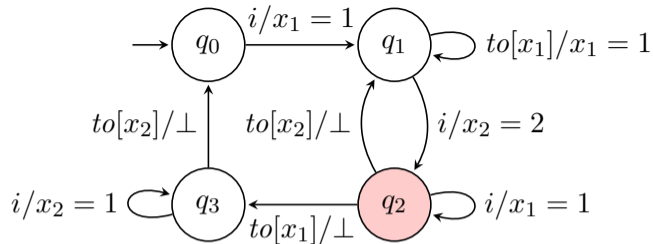
Let us illustrate using our run with unavoidable concurrencies.



$$(q_0, \emptyset, \emptyset) \xrightarrow{\tau} (q_0, \emptyset, \emptyset)$$

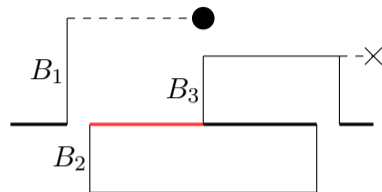
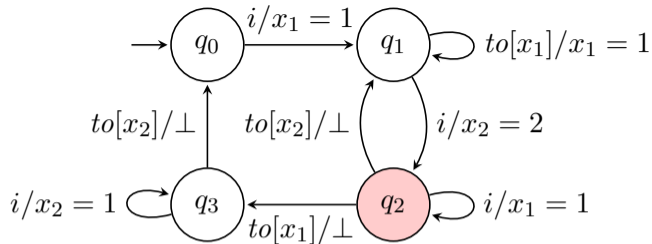


$$(q_0, \emptyset, \emptyset) \xrightarrow{\tau} (q_0, \emptyset, \emptyset) \xrightarrow{(i, x_1)} (q_1, x_1 = 1, \emptyset)$$

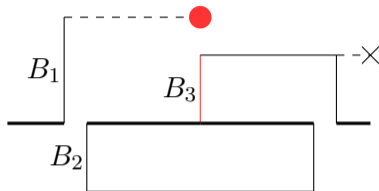
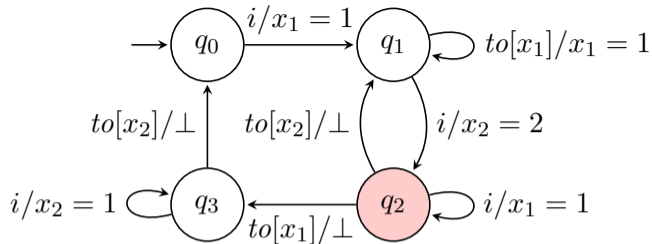


$$(q_0, \emptyset, \emptyset) \xrightarrow{\tau} (q_0, \emptyset, \emptyset) \xrightarrow{(i, x_1)} (q_1, x_1 = 1, \emptyset) \xrightarrow{(i, x_2)} (q_2, x_1 = 1 \wedge x_2 = 2, \emptyset)$$

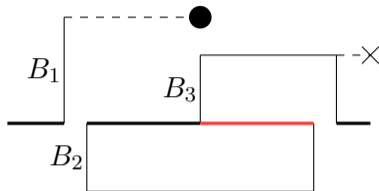
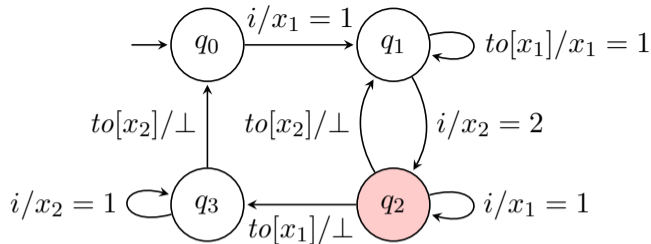




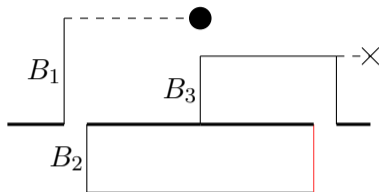
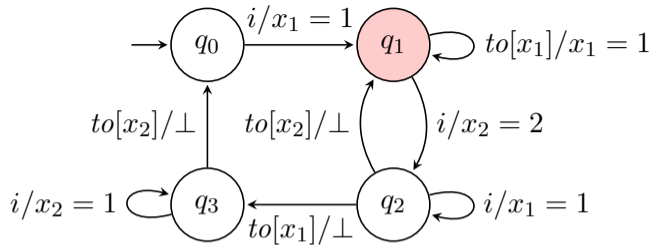
$$\begin{aligned}
 (q_0, \emptyset, \emptyset) &\xrightarrow{\tau} (q_0, \emptyset, \emptyset) \xrightarrow{(i, x_1)} (q_1, x_1 = 1, \emptyset) \xrightarrow{(i, x_2)} (q_2, x_1 = 1 \wedge x_2 = 2, \emptyset) \\
 &\xrightarrow{\tau} (q_2, 0 < x_1 < 1 \wedge x_2 - x_1 = 1, \emptyset) \xrightarrow{\tau} (q_2, x_1 = 0 \wedge x_2 = 1, \emptyset)
 \end{aligned}$$



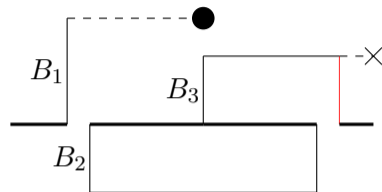
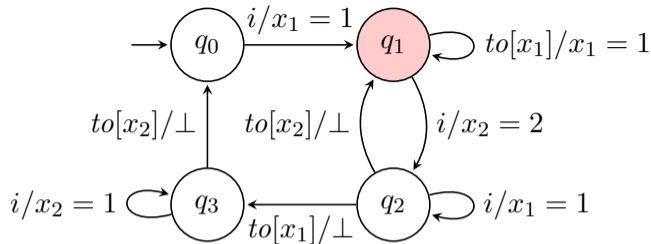
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 &\xrightarrow{(i, x_1)} (q_2, x_1 = 1 = x_2, \{x_1\}) \xrightarrow{\text{di}[x_1]} (q_2, x_1 = 1 = x_2, \emptyset)
 \end{aligned}$$



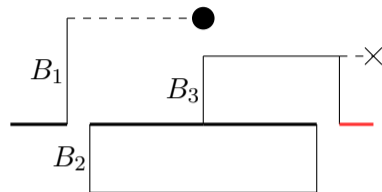
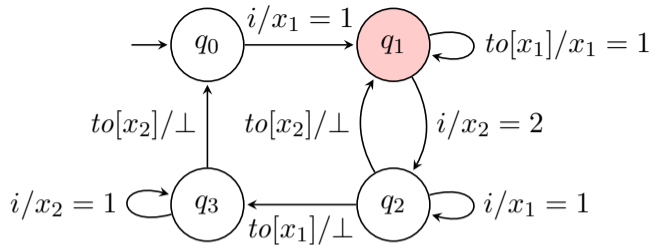
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 &\xrightarrow{(to[x_2], \perp)} (q_1, x_1 = 0, \emptyset)
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 &\xrightarrow{(to[x_2], \perp)} (q_1, x_1 = 0, \emptyset) \xrightarrow{(to[x_1], x_1)} (q_1, x_1 = 1, \emptyset) \xrightarrow{\tau} (q_1, 0 < x_1 < 1, \emptyset)
 \end{aligned}$$

We need to express the following:

- ▶ Two symbols are in concurrency iff there is no  $\tau$  in between.
- ▶ Two symbols are in the same block iff there is no transition using the timer of the block.
- ▶ There exists a cycle in the block graph.

The formula can be written with three quantifiers alternations  $\rightsquigarrow$  3EXP.

### Theorem 5 (Contribution)

*Fix an automaton and a state  $q$ . Deciding whether there exists an execution of the automaton that reaches  $q$  is PSPACE-complete.*



### Theorem 6 (Contribution)

*Deciding whether an AT contains an execution in which some concurrency **cannot** be avoided is PSPACE-hard and in 3EXP.*

# Thank you!

For all details, see Bruyère et al., “Automata with Timers”, 2023.



-  Angluin, Dana. “Learning Regular Sets from Queries and Counterexamples”. In: *Inf. Comput.* 75.2 (1987), pp. 87–106. DOI: [10.1016/0890-5401\(87\)90052-6](https://doi.org/10.1016/0890-5401(87)90052-6).
-  Bruyère, Véronique et al. “Automata with Timers”. In: *CoRR* abs/2305.07451 (2023). DOI: [10.48550/arXiv.2305.07451](https://doi.org/10.48550/arXiv.2305.07451). arXiv: 2305.07451. URL: <https://doi.org/10.48550/arXiv.2305.07451>.

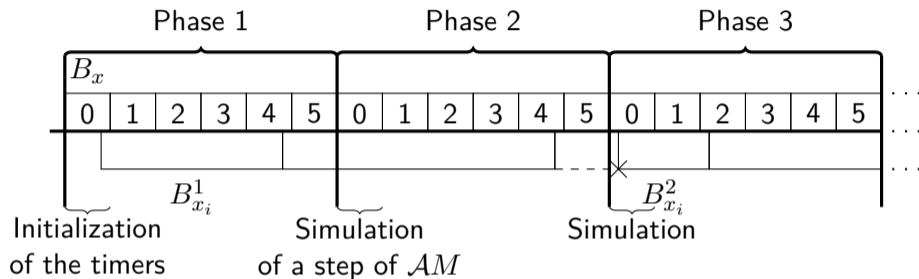


Figure 15: The beginning of a run for the reachability PSPACE-hardness proof.

Let  $\mathcal{A} = (X, I, Q, q_0, \chi, \delta)$  be an automaton with timers. For a timer  $x \in X$ ,  $c_x$  denotes the largest constant to which  $x$  is updated in  $\mathcal{A}$ . Let  $C = \max_{x \in X} c_x$ .

Two valuations  $\kappa$  and  $\kappa'$  are said *timer-equivalent*, noted  $\kappa \cong \kappa'$ , iff  $\text{dom}(\kappa) = \text{dom}(\kappa')$  and the following hold for all  $x_1, x_2 \in \text{dom}(\kappa)$ :

- ▶  $\lfloor \kappa(x_1) \rfloor = \lfloor \kappa'(x_1) \rfloor$ ,
- ▶  $\text{frac}(\kappa(x_1)) = 0$  iff  $\text{frac}(\kappa'(x_1)) = 0$ ,
- ▶  $\text{frac}(\kappa(x_1)) \leq \text{frac}(\kappa(x_2))$  iff  $\text{frac}(\kappa'(x_1)) \leq \text{frac}(\kappa'(x_2))$ .

A *timer region* for  $\mathcal{A}$  is an equivalence class of timer valuations induced by  $\cong$ . We lift the relation to configurations:  $(q, \kappa) \cong (q', \kappa')$  iff  $\kappa \cong \kappa'$  and  $q = q'$ . Finally,  $\llbracket (q, \kappa) \rrbracket_{\cong}$  denotes the equivalence class of  $(q, \kappa)$ .

We are now able to define a finite automaton called the *region automaton* of  $\mathcal{A}$  and denoted  $\mathcal{R}$ . The alphabet of  $\mathcal{R}$  is  $\Sigma = \{\tau\} \cup \hat{I}$  where  $\tau$  is a special symbol used in non-zero delay transitions. Formally,  $\mathcal{R}$  is the finite automaton  $(\Sigma, S, s_0, \Delta)$  where:

- ▶  $S = \{(q, \kappa) \mid q \in Q, \kappa \in \text{Val}(\chi(q))\} /_{\cong}$ , i.e., the quotient of the configurations by  $\cong$ , is the set of states,
- ▶  $s_0 = (q_0, \llbracket \kappa_0 \rrbracket_{\cong})$  with  $\kappa_0$  the empty valuation, is the initial state,
- ▶ the set of transitions  $\Delta \subseteq S \times \Sigma \times S$  includes  $(\llbracket (q, \kappa) \rrbracket_{\cong}, \tau, \llbracket (q, \kappa') \rrbracket_{\cong})$  if  $(q, \kappa) \xrightarrow{d} (q, \kappa')$  in  $\mathcal{A}$  whenever  $d > 0$ , and  $(\llbracket (q, \kappa) \rrbracket_{\cong}, i, \llbracket (q', \kappa') \rrbracket_{\cong})$  if  $(q, \kappa) \xrightarrow[u]{i} (q', \kappa')$  in  $\mathcal{A}$ .

### Lemma 7

Let  $\mathcal{A} = (X, I, Q, q_0, \chi, \delta)$  be an automaton with timers and  $\mathcal{R}$  be its region automaton.

1. The size of  $\mathcal{R}$  is linear in  $|Q|$  and exponential in  $|X|$ . That is,  $|S|$  is smaller than or equal to  $|Q| \cdot |X|! \cdot 2^{|X|} \cdot (C + 1)^{|X|}$ .
2. There is a timed run  $\rho$  of  $\mathcal{A}$  that begins in  $(q, \kappa)$  and ends in  $(q', \kappa')$  iff there is a run  $\rho'$  of  $\mathcal{R}$  that begins in  $\llbracket (q, \kappa) \rrbracket_{\cong}$  and ends in  $\llbracket (q', \kappa') \rrbracket_{\cong}$ .

## Corollary 8

Let  $\mathcal{A}$  be an automaton with timers and  $\rho \in \text{ptruns}(\mathcal{A})$  be a padded timed run with races. Suppose that  $G_\rho$  is cyclic. Then there exists a cycle  $\mathcal{C}$  in  $G_\rho$  such that

- ▶ any block of  $\mathcal{C}$  participates in exactly two races described by this cycle,
- ▶ for any race described by  $\mathcal{C}$ , exactly two blocks of  $\mathcal{C}$  participate in the race,
- ▶ the blocks  $B = (k_1 \dots k_m, \gamma)$  of  $\mathcal{C}$  satisfy either  $m \geq 2$ , or  $m = 1$  and  $\gamma = \bullet$ .