

Active Learning of Mealy Machines with Timers

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Gaëtan Staquet, Frits W. Vaandrager

November 20, 2024



Many computer systems have **timing** constraints:

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BUT timed Mealy machines are hard to construct and understand.

We focus on systems that can be represented with **timers**: **Mealy machines with timers.**

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- ▶ Learning timed Mealy machines is challenging.

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- ▶ This work: learning algorithm.

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A Mealy machine with timers

(MMT) is a tuple

$\mathcal{M} = (X, I, O, Q, q_0, \delta)$ where

- ▶ X is the set of **timers**;
- ▶ I is the set of **inputs**; the set of all **actions** is:

$$I \cup \{to[x] \mid x \in X\};$$

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- ▶ δ is the transition function.

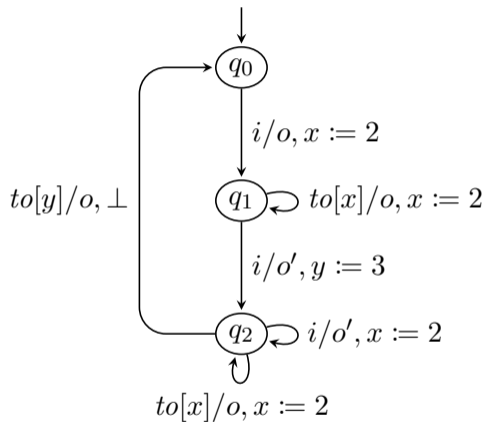
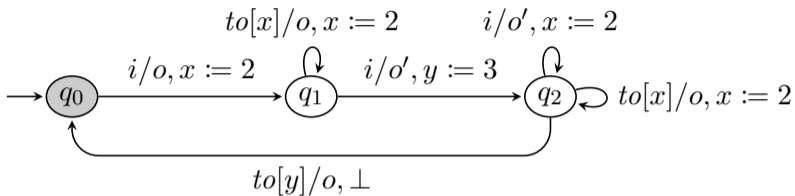
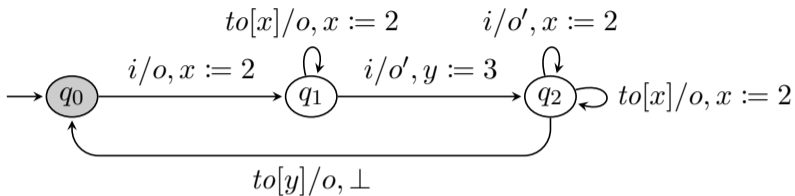


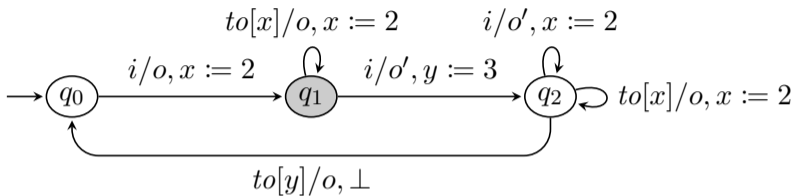
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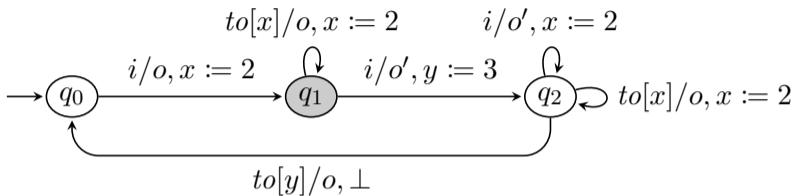
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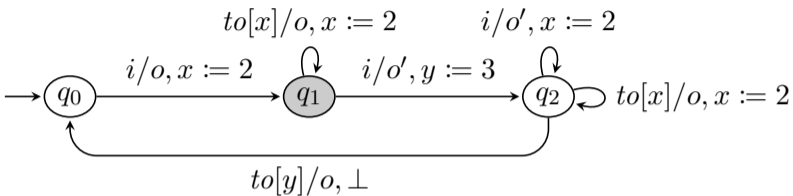
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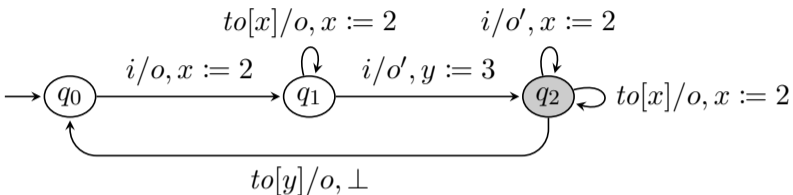
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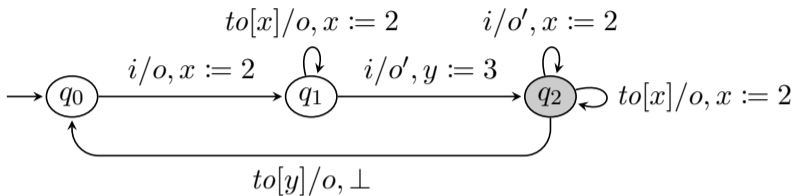
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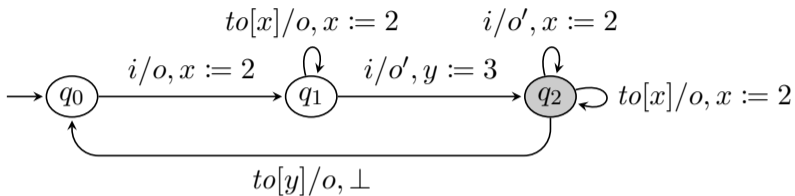
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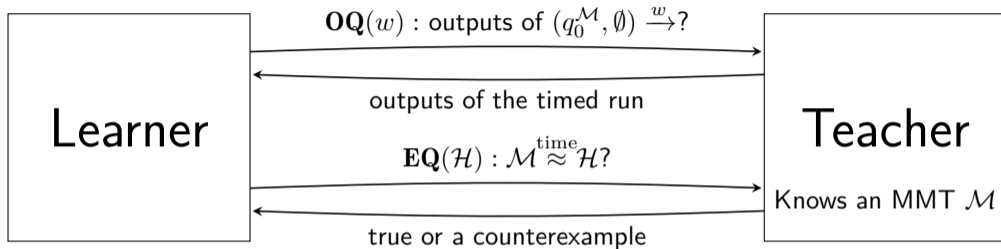


Figure 2: Adaptation of Angluin's framework² to MMTs.

²Angluin, "Learning Regular Sets from Queries and Counterexamples", 1987; Shahbaz and Groz, "Inferring mealy machines", 2009.

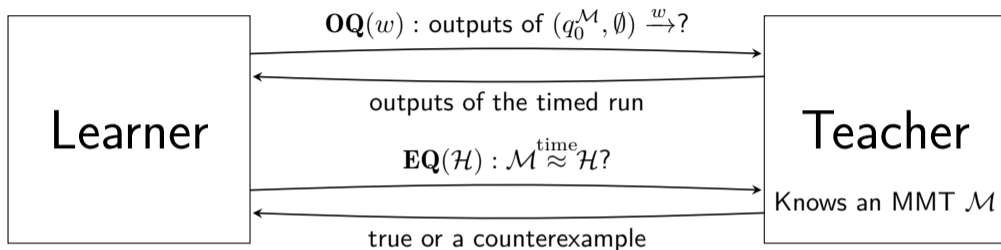


Figure 2: Adaptation of Angluin's framework² to MMTs.

Both queries are in the **timed** world... Cumbersome to use!

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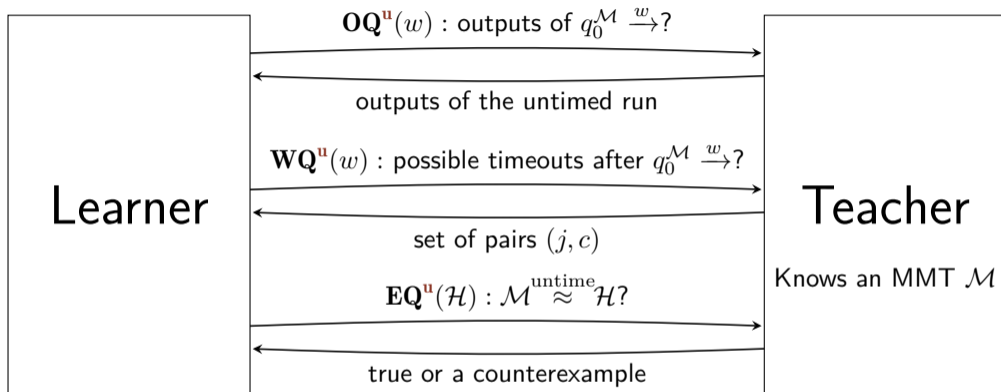


Figure 3: Untimed adaptation of Angluin's framework to MMTs.

We stay in the **untimed** world!

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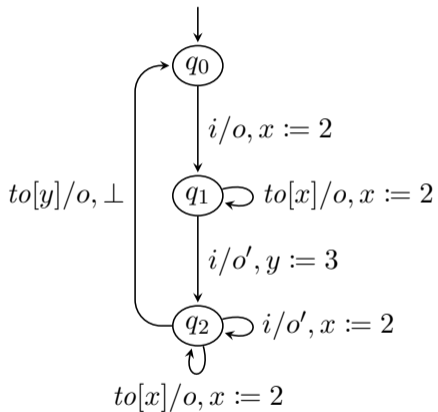
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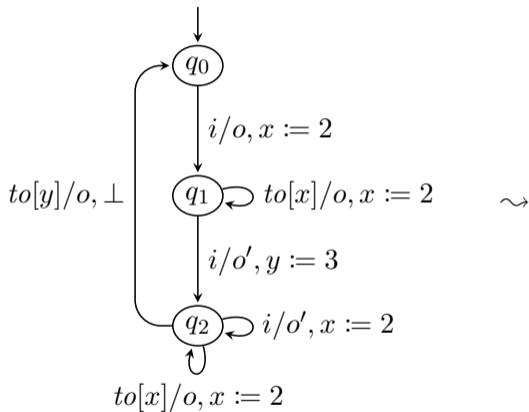
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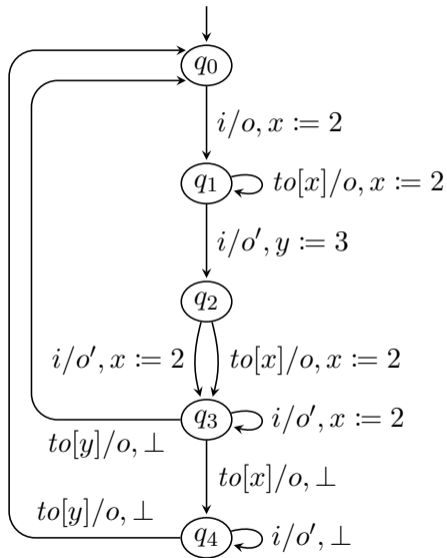
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Proposition 2. *It is possible to construct an MMT in which the second condition is satisfied.*





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We adapt $L^\#$ (active learning algorithm for Mealy machines³) to MMTs: $L^\#_{\text{MMT}}$.

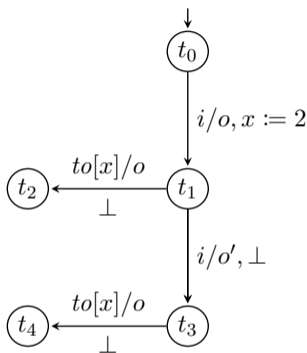
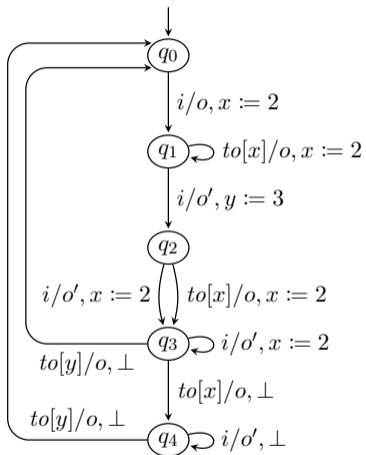
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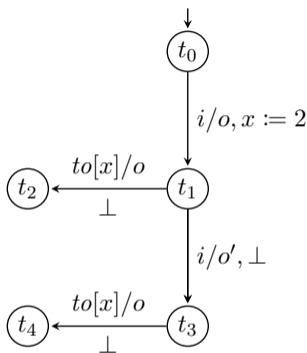
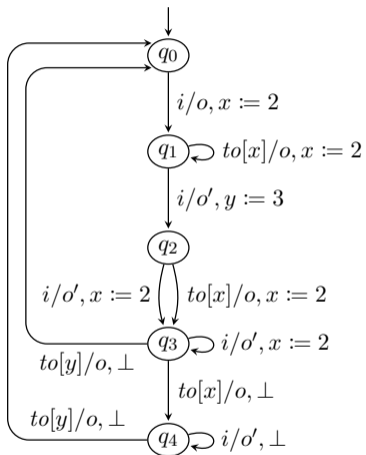
Theorem 3. Let \mathcal{M} be a “good” MMT and ℓ be the length of the longest counterexample returned by the teacher. Then,

- ▶ the $L^\#_{\text{MMT}}$ algorithm eventually terminates and returns an MMT \mathcal{N} such that $\mathcal{M}^{\text{time}} \approx \mathcal{N}$ and whose size is **polynomial** in $|Q^\mathcal{M}|$ and **factorial** in $|X^\mathcal{M}|$, and
- ▶ in time and number of untimed queries **polynomial** in $|Q^\mathcal{M}|, |I|$, and ℓ , and **factorial** in $|X^\mathcal{M}|$.

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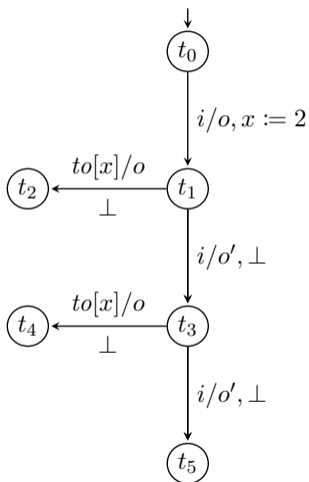
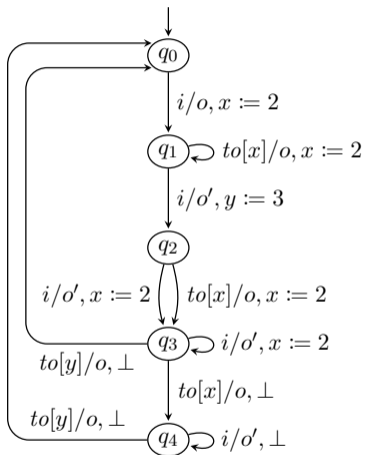


We want to add $i \cdot i \cdot i$ and the potential timeouts.



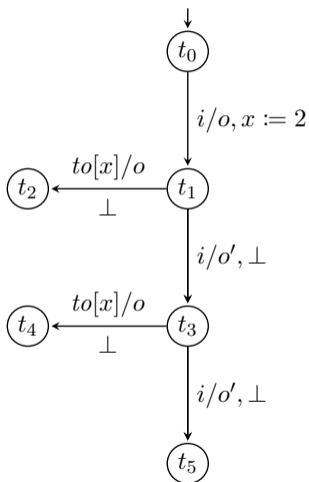
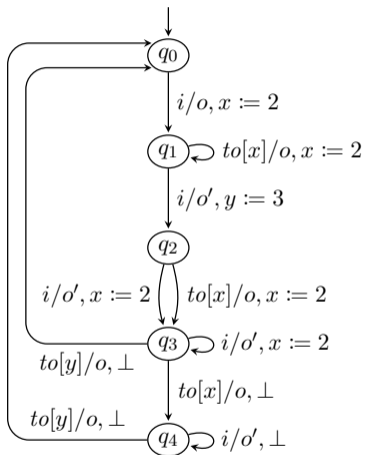
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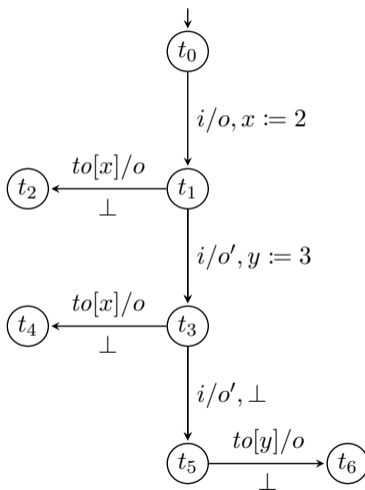
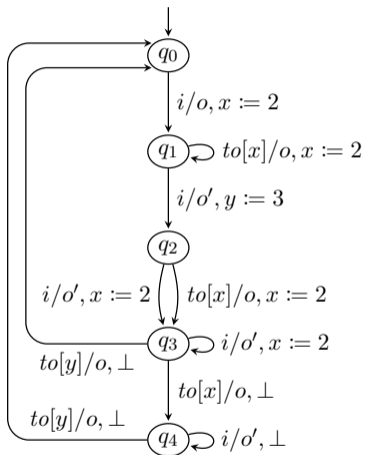
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- ▶ $\mathbf{OQ}^u(i \cdot i \cdot i) \rightsquigarrow o \cdot o' \cdot o'$.
- ▶ So, $t_3 \xrightarrow[i/o']{i/o'} t_5$.



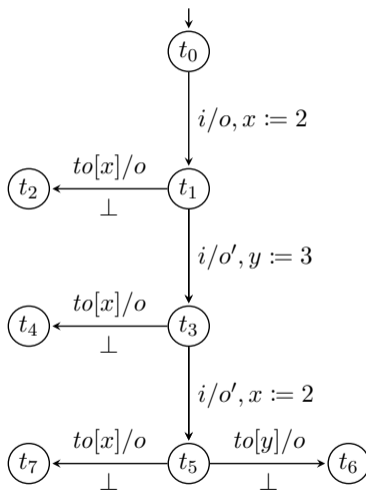
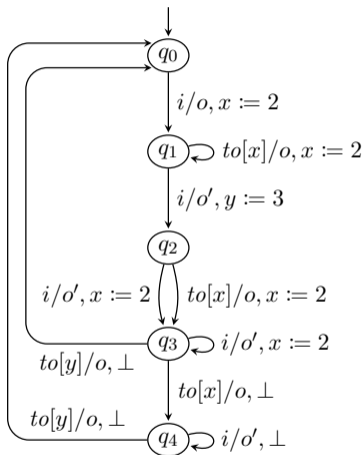
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- ▶ And $t_3 \xrightarrow{i} t_5$ starts a timer at constant 2.

We implemented $L^{\#}_{\text{MMT}}$ in Rust⁴ and ran some experiments.

| Model | $ Q $ | $ I $ | $ X $ | $ WQ^u $ | $ OQ^u $ | $ EQ^u $ | Time[msecs] |
|-----------------|-------|-------|-------|----------|----------|----------|-------------|
| AKM | 4 | 5 | 1 | 22 | 35 | 2 | 684 |
| CAS | 8 | 4 | 1 | 60 | 89 | 3 | 1344 |
| Light | 4 | 2 | 1 | 10 | 13 | 2 | 302 |
| PC | 8 | 9 | 1 | 75 | 183 | 4 | 2696 |
| TCP | 11 | 8 | 1 | 123 | 366 | 8 | 3182 |
| Train | 6 | 3 | 1 | 32 | 28 | 3 | 1559 |
| Running example | 3 | 1 | 2 | 11 | 5 | 2 | 1039 |
| FDDI 1-station | 9 | 2 | 2 | 32 | 20 | 1 | 1105 |
| Oven | 12 | 5 | 1 | 907 | 317 | 3 | 9452 |
| WSN | 9 | 4 | 1 | 175 | 108 | 4 | 3291 |

⁴https://gitlab.science.ru.nl/bharat/mmt_lsharp.

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Thank you!





For all details, see

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Part I – Appendix

Appendix

References I

-  Angluin, Dana. “Learning Regular Sets from Queries and Counterexamples”. In: *Inf. Comput.* 75.2 (1987), pp. 87–106. DOI: [10.1016/0890-5401\(87\)90052-6](https://doi.org/10.1016/0890-5401(87)90052-6).
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References II

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