Active Learning of Mealy Machines with Timers

Véronique Bruyère, Bharat Garhewal, Guillermo A. Pérez, Gaëtan Staquet, Frits W. Vaandrager

February 6, 2025













Experimental results 00

Many computer systems have timing constraints:

- Network protocols;
- Schedulers;
- Embedded systems;
- In general, real-time systems.

Experimental results

Many computer systems have timing constraints:

- Network protocols;
- Schedulers;
- Embedded systems;
- In general, real-time systems.

Well-known model for these systems: timed Mealy machines.

Experimental results

Many computer systems have timing constraints:

- Network protocols;
- Schedulers;
- Embedded systems;
- In general, real-time systems.

Well-known model for these systems: timed Mealy machines.

In short: finite Mealy machines augmented with **clocks** that can be reset or used in guards along transitions and states.

Experimental results

Many computer systems have timing constraints:

- Network protocols;
- Schedulers;
- Embedded systems;
- In general, real-time systems.

Well-known model for these systems: timed Mealy machines.

In short: finite Mealy machines augmented with **clocks** that can be reset or used in guards along transitions and states.

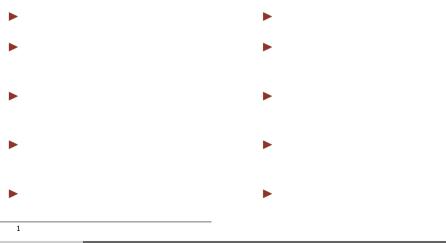
BUT timed Mealy machines are hard to construct and understand.

Experimental results

We focus on systems that can be represented with **timers**: **Mealy machines with timers**.

Timed Mealy machines

Mealy machines with timers



Timed Mealy machines

Clocks go from 0 to infinity;

Mealy machines with timers

► Timers go from a given value to 0;

Timed Mealy machines

- Clocks go from 0 to infinity;
- ► We can test the current value of the clocks;

Mealy machines with timers

- ► Timers go from a given value to 0;
- ▶ We can only test if a timer is zero;



Timed Mealy machines

- Clocks go from 0 to infinity;
- ► We can test the current value of the clocks;
- ► Timed Mealy machines are more expressive;

Mealy machines with timers

- ► Timers go from a given value to 0;
- ▶ We can only test if a timer is zero;
- ► Mealy machines with timers are more restrictive;

Timed Mealy machines

- Clocks go from 0 to infinity;
- ► We can test the current value of the clocks;
- ► Timed Mealy machines are more expressive;
- Well-known model;

Mealy machines with timers

- ► Timers go from a given value to 0;
- ▶ We can only test if a timer is zero;
- ► Mealy machines with timers are more restrictive;
- ► We previously studied some properties of Mealy machines with timers;¹

¹Bruyère, Pérez, et al., "Automata with Timers", 2023

Timed Mealy machines

- Clocks go from 0 to infinity;
- ► We can test the current value of the clocks;
- ► Timed Mealy machines are more expressive;
- Well-known model;

Mealy machines with timers

- ► Timers go from a given value to 0;
- ► We can only test if a timer is zero;
- ► Mealy machines with timers are more restrictive;
- ► We previously studied some properties of Mealy machines with timers;¹
- ► Learning timed Mealy machines is ► This work: learning algorithm. challenging.

¹Bruyère, Pérez, et al., "Automata with Timers", 2023

G. Staquet

Experimental results

A Mealy machine with timers (MMT) is a tuple $\mathcal{M} = (X, I, O, Q, q_0, \delta) \text{ where }$

- ► X is the set of **timers**;
- I is the set of inputs; the set of all actions is:

 $I \cup \{to[x] \mid x \in X\};$

O is the set of outputs;

Syntax and semantics

Learning algorithm

Experimental results

- A Mealy machine with timers (MMT) is a tuple $\mathcal{M} = (X, I, O, Q, q_0, \delta)$ where
 - ► X is the set of **timers**;
 - I is the set of inputs; the set of all actions is:

 $I \cup \{to[x] \mid x \in X\};$

- *O* is the set of **outputs**;
- Q is the finite set of states;
- $\blacktriangleright \ q_0 \in Q$ is the initial state;





Figure 1: An MMT.

 q_2

Syntax and semantics

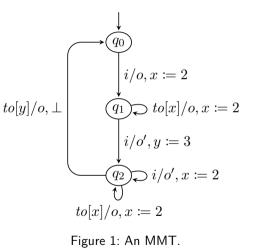
Learning algorithm

Experimental results

- A Mealy machine with timers (MMT) is a tuple $\mathcal{M} = (X, I, O, Q, q_0, \delta)$ where
 - ► X is the set of **timers**;
 - I is the set of inputs; the set of all actions is:

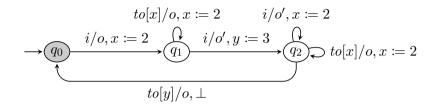
 $I \cup \{to[x] \mid x \in X\};$

- *O* is the set of **outputs**;
- Q is the finite set of states;
- $\blacktriangleright \ q_0 \in Q \text{ is the initial state;}$
- $\blacktriangleright \delta$ is the transition function.



Syntax and semantics

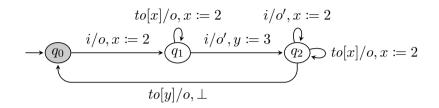
Learning algorithm 0000000 Experimental results



 (q_0, \emptyset)

Syntax and semantics

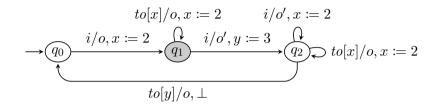
Learning algorithm 0000000 Experimental results



 $(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset)$

Syntax and semantics

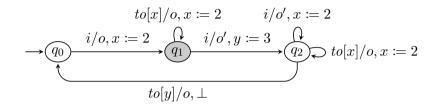
Learning algorithm 0000000



$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow{i/o} (q_1, x = 2)$$

Syntax and semantics

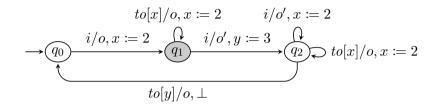
Learning algorithm 0000000



$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow{i/o} (q_1, x = 2) \xrightarrow{2} (q_1, x = 0)$$

Syntax and semantics

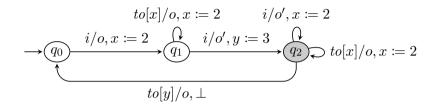
Learning algorithm 0000000



$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow{i/o} (q_1, x = 2) \xrightarrow{2} (q_1, x = 0) \xrightarrow{to[x]/o} (q_1, x = 2)$$

Syntax and semantics

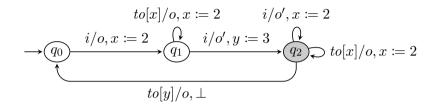
Learning algorithm 0000000



$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow{i/o} (q_1, x = 2) \xrightarrow{2} (q_1, x = 0) \xrightarrow{to[x]/o} (q_1, x = 2)$$
$$\xrightarrow{0} (q_1, x = 2) \xrightarrow{i/o'} (q_2, x = 2, y = 3)$$

Syntax and semantics

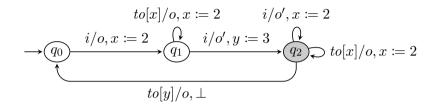
Learning algorithm 0000000



$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow{i/o} (q_1, x = 2) \xrightarrow{2} (q_1, x = 0) \xrightarrow{to[x]/o} (q_1, x = 2)$$
$$\xrightarrow{0} (q_1, x = 2) \xrightarrow{i/o'} (q_2, x = 2, y = 3) \xrightarrow{2} (q_2, x = 0, y = 1)$$

Syntax and semantics

Learning algorithm 0000000



$$(q_0, \emptyset) \xrightarrow{1} (q_0, \emptyset) \xrightarrow{i/o} (q_1, x = 2) \xrightarrow{2} (q_1, x = 0) \xrightarrow{to[x]/o} (q_1, x = 2)$$
$$\xrightarrow{0} (q_1, x = 2) \xrightarrow{i/o'} (q_2, x = 2, y = 3) \xrightarrow{2} (q_2, x = 0, y = 1)$$
$$\xrightarrow{i/o'} (q_2, x = 2, y = 1) \xrightarrow{0.5} (q_2, x = 1.5, y = 0.5).$$

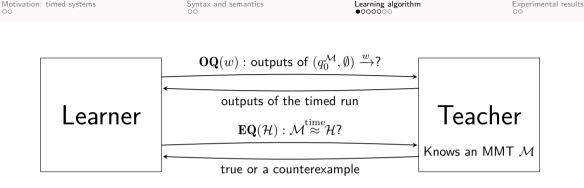


Figure 2: Adaptation of Angluin's framework² to MMTs.

²Angluin, "Learning Regular Sets from Queries and Counterexamples", 1987.

G. Staquet

Learning algorithm — Framework

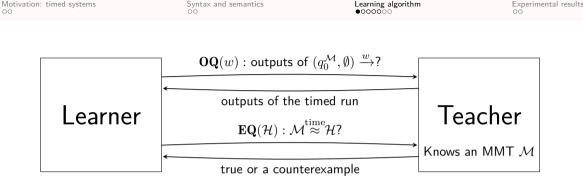


Figure 2: Adaptation of Angluin's framework² to MMTs.

Two problems:

> Set of timers of \mathcal{M} is unknown to the learner. \sim Hide the timeouts via the delays.

G. Staquet

²Angluin, "Learning Regular Sets from Queries and Counterexamples", 1987.

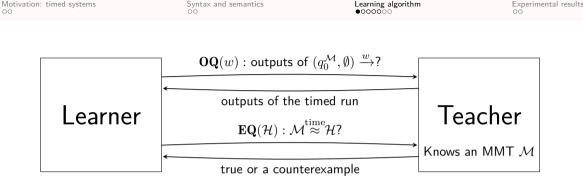


Figure 2: Adaptation of Angluin's framework² to MMTs.

Two problems:

- **>** Set of timers of \mathcal{M} is unknown to the learner. \sim Hide the timeouts via the delays.
- Both queries are in the timed world... Cumbersome to use!

²Angluin, "Learning Regular Sets from Queries and Counterexamples", 1987.

G. Staquet



Learning algorithm ○●○○○○○ Experimental results

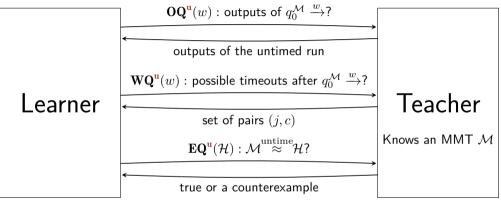


Figure 3: Untimed adaptation of Angluin's framework to MMTs.

We stay in the **untimed** world!

Syntax and semantics

Learning algorithm

Experimental results

Question. How to hide the names of the timers for the untimed queries?

Motivation: timed systems	Syntax and semantics	Learning algorithm	Experimental results
00	00	000000	00

Question. How to hide the names of the timers for the untimed queries?

$$\xrightarrow[x:=2]{i/o} \cdot \xrightarrow[x:=2]{i/o'} \cdot \xrightarrow[y:=3]{i/o'} \cdot \xrightarrow[x:=2]{to[y]/o} \cdot \xrightarrow[to[y]/o}$$

.

Motivation: timed systems 00	Syntax and semantics	Learning algorithm	Experimental results

Question. How to hide the names of the timers for the untimed queries?

$$\cdot \xrightarrow{i/o} \frac{io[x]/o}{x \coloneqq 2} \cdot \xrightarrow{to[x]/o} \frac{i/o'}{y \coloneqq 3} \cdot \xrightarrow{to[x]/o'} \frac{to[y]/o}{x \coloneqq 2} \cdot \xrightarrow{to[y]/o} \perp$$

becomes

$$\cdot \xrightarrow[x:=2]{i/o} \cdot \xrightarrow[x:=2]{i/o} \cdot \xrightarrow[y:=3]{i/o'} \cdot \xrightarrow{to[2]/o'} \cdot \xrightarrow[to[3]/o} \cdot$$

Does not hold for all MMTs!

Does **not** hold for all MMTs! It holds when an MMT is **good**:

timeouts are observed via their outputs,

Does **not** hold for all MMTs! It holds when an MMT is **good**:

- timeouts are observed via their outputs,
- for every untimed sequence of transitions, there exists a timed run using exactly this sequence of transitions...

Does **not** hold for all MMTs! It holds when an MMT is **good**:

- timeouts are observed via their outputs,
- for every untimed sequence of transitions, there exists a timed run using exactly this sequence of transitions...
- with all delays > 0 and there is at most one timer that times out at any time (see Bruyère, Pérez, et al., "Automata with Timers", 2023).

Does **not** hold for all MMTs! It holds when an MMT is **good**:

- timeouts are observed via their outputs,
- for every untimed sequence of transitions, there exists a timed run using exactly this sequence of transitions...
- with all delays > 0 and there is at most one timer that times out at any time (see Bruyère, Pérez, et al., "Automata with Timers", 2023).

Proposition 2. It is possible to construct an MMT in which the second condition is satisfied.

Syntax and semantics

Learning algorithm 0000€00

Syntax and semantics

Learning algorithm 0000€00 Experimental results

Syntax and semantics

Learning algorithm ○○○○○●○ Experimental results

We adapt $L^{\#}$ (active learning algorithm for Mealy machines³) to MMTs: $L^{\#}_{MMT}$.

³Vaandrager et al., "A New Approach for Active Automata Learning Based on Apartness", 2022.

Syntax and semantics

Learning algorithm ○○○○○●○

We adapt $L^{\#}$ (active learning algorithm for Mealy machines³) to MMTs: $L^{\#}_{MMT}$.

Theorem 3. Let \mathcal{M} be a "good" MMT and ℓ be the length of the longest counterexample returned by the teacher. Then,

- the $L_{MMT}^{\#}$ algorithm eventually terminates and returns an MMT \mathcal{N} such that $\mathcal{M} \stackrel{\text{time}}{\approx} \mathcal{N}$ and whose size is **polynomial** in $|Q^{\mathcal{M}}|$ and **factorial** in $|X^{\mathcal{M}}|$, and
- ▶ in time and number of untimed queries **polynomial** in $|Q^{\mathcal{M}}|, |I|$, and ℓ , and **factorial** in $|X^{\mathcal{M}}|$.

³Vaandrager et al., "A New Approach for Active Automata Learning Based on Apartness", 2022.

Syntax and semantics

Learning algorithm ○○○○○○● Experimental results

We want to add $i \cdot i \cdot i$ and the potential timeouts.

 t_0 q_0 $i/o, x \coloneqq 2$ $i/o, x_1 \coloneqq 2$ $\begin{array}{c} \hline q_1 & to[x]/o, x \coloneqq 2 \\ \hline i/o', y \coloneqq 3 \end{array}$ $to[x_1]/o$ t_2 (q_2) $i/o', \perp$ $to[x_1]/o$ $\begin{array}{c} i/o', x \coloneqq 2 () to[x]/o, x \coloneqq 2 \\ \hline to[y]/o, \bot \\ \hline to[y]/o, \bot \\ \hline to[y]/o, \bot \\ \hline q_4 \\ \hline i/o', \bot \\ \hline q_4 \\ \hline i/o', \bot \end{array}$

Syntax and semantics

 t_0

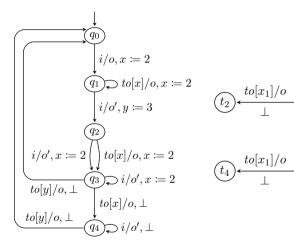
 $i/o, x_1 \coloneqq 2$

 $i/o', \perp$

Learning algorithm ○○○○○○● Experimental results

We want to add $i \cdot i \cdot i$ and the potential timeouts.

 $\blacktriangleright \mathbf{OQ^{u}}(i \cdot i \cdot i) \rightsquigarrow o \cdot o' \cdot o'.$



Syntax and semantics

Learning algorithm ○○○○○○● Experimental results

We want to add $i \cdot i \cdot i$ and the potential timeouts.

- $\blacktriangleright \mathbf{OQ^{u}}(i \cdot i \cdot i) \rightsquigarrow o \cdot o' \cdot o'.$
- $\blacktriangleright \text{ So, } t_3 \xrightarrow[]{i/o'} t_5.$

 t_0 q_0 $i/o, x \coloneqq 2$ $i/o, x_1 \coloneqq 2$ $\begin{array}{c} \hline q_1 & \text{to}[x]/o, x \coloneqq 2 \\ \hline i/o', y \coloneqq 3 \end{array}$ $to[x_1]/o$ t_2 (q_2) $i/o', \perp$ $\begin{array}{c} i/o', x \coloneqq 2 \\ \downarrow to[x]/o, x \coloneqq 2 \\ \hline q_3 \\ \downarrow to[y]/o, \bot \\ \hline to[y]/o, \bot \\ \hline q_4 \\ \downarrow o[x]/o, \bot \\ \hline q_4 \\ \downarrow o', \bot \end{array}$ (t_4) \leftarrow $to[x_1]/o$ $i/o', \perp$ t_5

Syntax and semantics

 t_0

 $i/o, x_1 \coloneqq 2$

 $i/o', \perp$

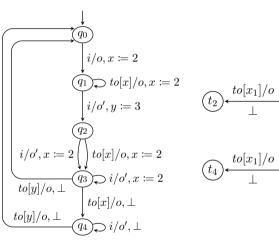
 $i/o', \perp$

 t_5

Learning algorithm ○○○○○○● Experimental results

We want to add $i \cdot i \cdot i$ and the potential timeouts.

- $\blacktriangleright \mathbf{OQ^{u}}(i \cdot i \cdot i) \rightsquigarrow o \cdot o' \cdot o'.$
- $\blacktriangleright \text{ So, } t_3 \xrightarrow[]{i/o'}{\perp} t_5.$
- $\blacktriangleright \mathbf{WQ^{u}}(i \cdot i \cdot i) \\ \sim \{(2,3), (3,2)\}.$

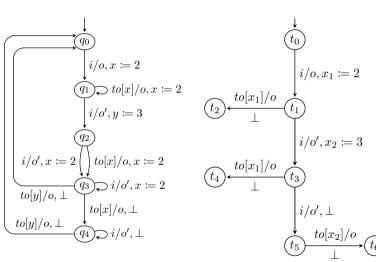


Syntax and semantics

Learning algorithm ○○○○○○● Experimental results

We want to add $i \cdot i \cdot i$ and the potential timeouts.

- $\blacktriangleright \mathbf{OQ^{u}}(i \cdot i \cdot i) \rightsquigarrow o \cdot o' \cdot o'.$
- $\blacktriangleright \text{ So, } t_3 \xrightarrow[]{i/o'}{\perp} t_5.$
- $\blacktriangleright \mathbf{WQ^{u}}(i \cdot i \cdot i)$ $\rightsquigarrow \{(2,3), (3,2)\}.$
- So, $t_1 \xrightarrow{i} t_3$ starts a timer at constant 3.



 q_0

 (q_2)

 $i/o', x \coloneqq 2 \bigcup to[x]/o, x \coloneqq 2$

 $\underbrace{to[y]/o, \bot}_{to[y]/o, \bot} \underbrace{ \begin{array}{c} \checkmark \checkmark \\ q_3 \\ \downarrow \\ to[x]/o, \bot \\ \hline to[x]/o, \bot \\ \hline q_4 \\ \bigcirc i/o', \bot \end{array}} i/o', x \coloneqq 2$

 $i/o, x \coloneqq 2$

 $\begin{array}{c} \hline q_1 \\ \hline \\ \hline \\ i/o', y \coloneqq 3 \end{array} to[x]/o, x \coloneqq 2$

Syntax and semantics

 t_0

 $to[x_1]/o$

 (t_4) \leftarrow $to[x_1]/o$

 $i/o, x_1 \coloneqq 2$

 $i/o', x_2 \coloneqq 3$

Learning algorithm ○○○○○○● Experimental results

We want to add $i \cdot i \cdot i$ and the potential timeouts.

- $\blacktriangleright \mathbf{OQ^{u}}(i \cdot i \cdot i) \rightsquigarrow o \cdot o' \cdot o'.$
- $\blacktriangleright \text{ So, } t_3 \xrightarrow[]{i/o'}{\perp} t_5.$
- $\blacktriangleright \mathbf{WQ^{u}}(i \cdot i \cdot i)$ $\rightsquigarrow \{(2,3), (3,2)\}.$
- So, $t_1 \xrightarrow{i} t_3$ starts a timer at constant 3.
- And $t_3 \xrightarrow{i} t_5$ starts a timer at constant 2.



Syntax and semantics

Learning algorithm

Experimental results

We implemented $L^{\#}_{\rm MMT}$ in Rust^4 and ran some experiments.

Model	Q	I	X	$ \mathbf{W}\mathbf{Q}^{\mathbf{u}} $	$ \mathbf{OQ^u} $	$ \mathbf{EQ}^{\mathbf{u}} $	Time[msecs]
AKM	4	5	1	22	35	2	684
CAS	8	4	1	60	89	3	1344
Light	4	2	1	10	13	2	302
PC	8	9	1	75	183	4	2696
ТСР	11	8	1	123	366	8	3182
Train	6	3	1	32	28	3	1559
Running example	3	1	2	11	5	2	1039
FDDI 1-station	9	2	2	32	20	1	1105
Oven	12	5	1	907	317	3	9452
WSN	9	4	1	175	108	4	3291

⁴https://gitlab.science.ru.nl/bharat/mmt_lsharp.

Motivation:	timed	systems
00		

Syntax and semantics

Learning algorithm

Experimental results

Still work to be done:

- Further experiments with more timers,
- Simplify the learning algorithm as much as possible.

Still work to be done:

- Further experiments with more timers,
- Simplify the learning algorithm as much as possible.

Thank you!

For all details, see

Bruyère, Garhewal, et al., "Active Learning of Mealy Machines with Timers", 2024.

Part I – Appendix

Appendix



References I

- Angluin, Dana. "Learning Regular Sets from Queries and Counterexamples". In: Inf. Comput. 75.2 (1987), pp. 87–106. DOI: 10.1016/0890-5401(87)90052-6.
- Bruyère, Véronique, Bharat Garhewal, et al. "Active Learning of Mealy Machines with Timers". In: CoRR abs/2403.02019 (2024). DOI: 10.48550/arXiv.2403.02019. arXiv: 2403.02019.
- Bruyère, Véronique, Guillermo A. Pérez, et al. "Automata with Timers". In: Formal Modeling and Analysis of Timed Systems - 21st International Conference, FORMATS 2023, Antwerp, Belgium, September 19-21, 2023, Proceedings. Ed. by Laure Petrucci and Jeremy Sproston. Vol. 14138. Lecture Notes in Computer Science. Springer, 2023, pp. 33–49. DOI: 10.1007/978–3–031–42626–1_3.

References II

Vaandrager, Frits W. et al. "A New Approach for Active Automata Learning Based on Apartness". In: Tools and Algorithms for the Construction and Analysis of Systems - 28th International Conference, TACAS 2022, Held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2022, Munich, Germany, April 2-7, 2022, Proceedings, Part I. Ed. by Dana Fisman and Grigore Rosu. Vol. 13243. Lecture Notes in Computer Science. Springer, 2022, pp. 223–243. DOI: 10.1007/978-3-030-99524-9_12.